

# Unmanned Aircraft Systems Risk Assessment: Review of Existing Tools and New Results



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# GOAL

To present a new Risk Assessment Tool for the operation of dual-use Unmanned Aerial Systems and compare its potential with other available Risk Assessment Tools.



# Outline

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Introduction

01

SORA

02

FAA Order 8130.34D

03

Risk Assessment Tool

04

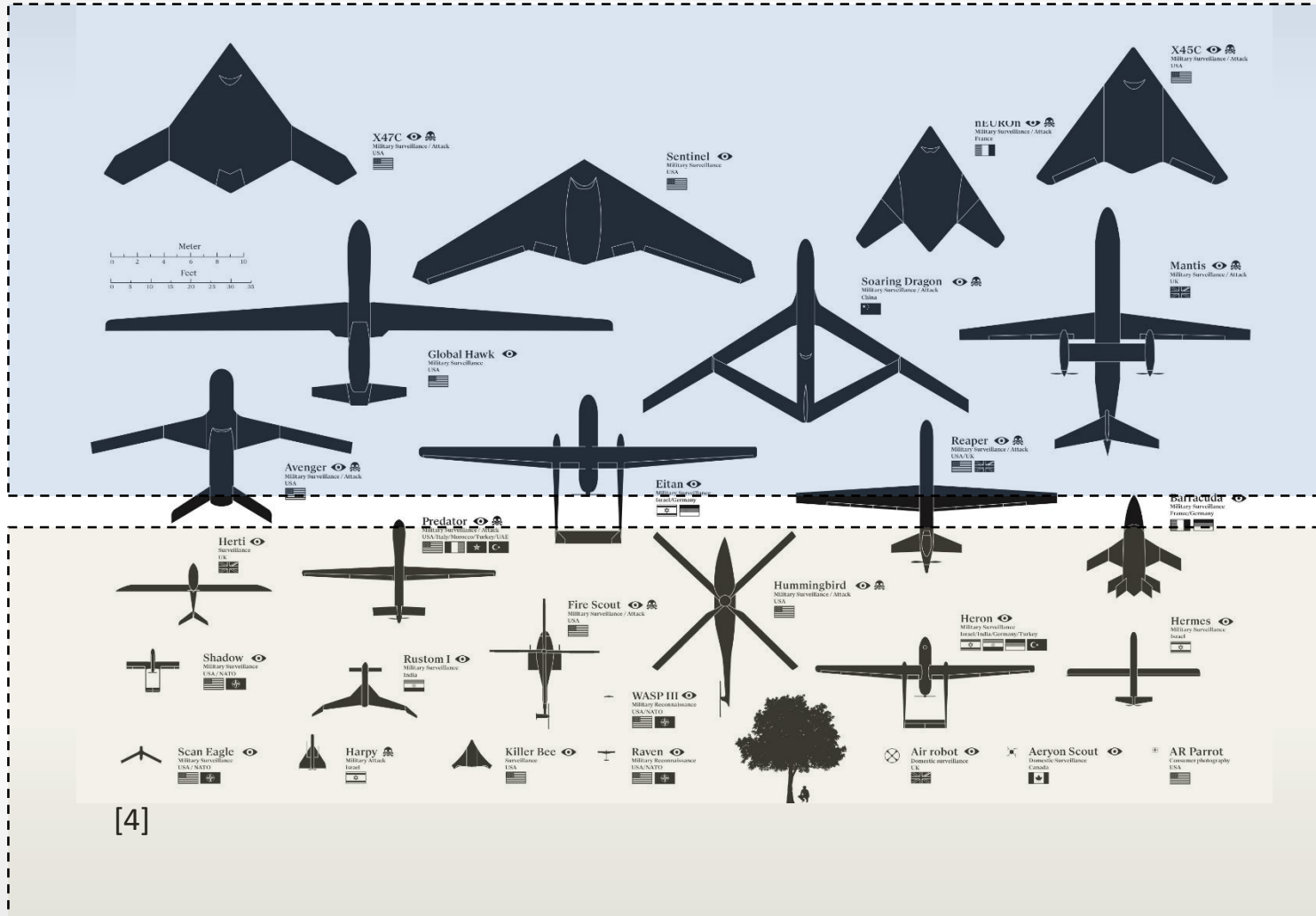
New/Proposed Risk Assessment Tool

05

Discussion

06

Conclusions



Unrestricted Operation



High Investment in tests  
High Certification Periods

Designed for specific operations



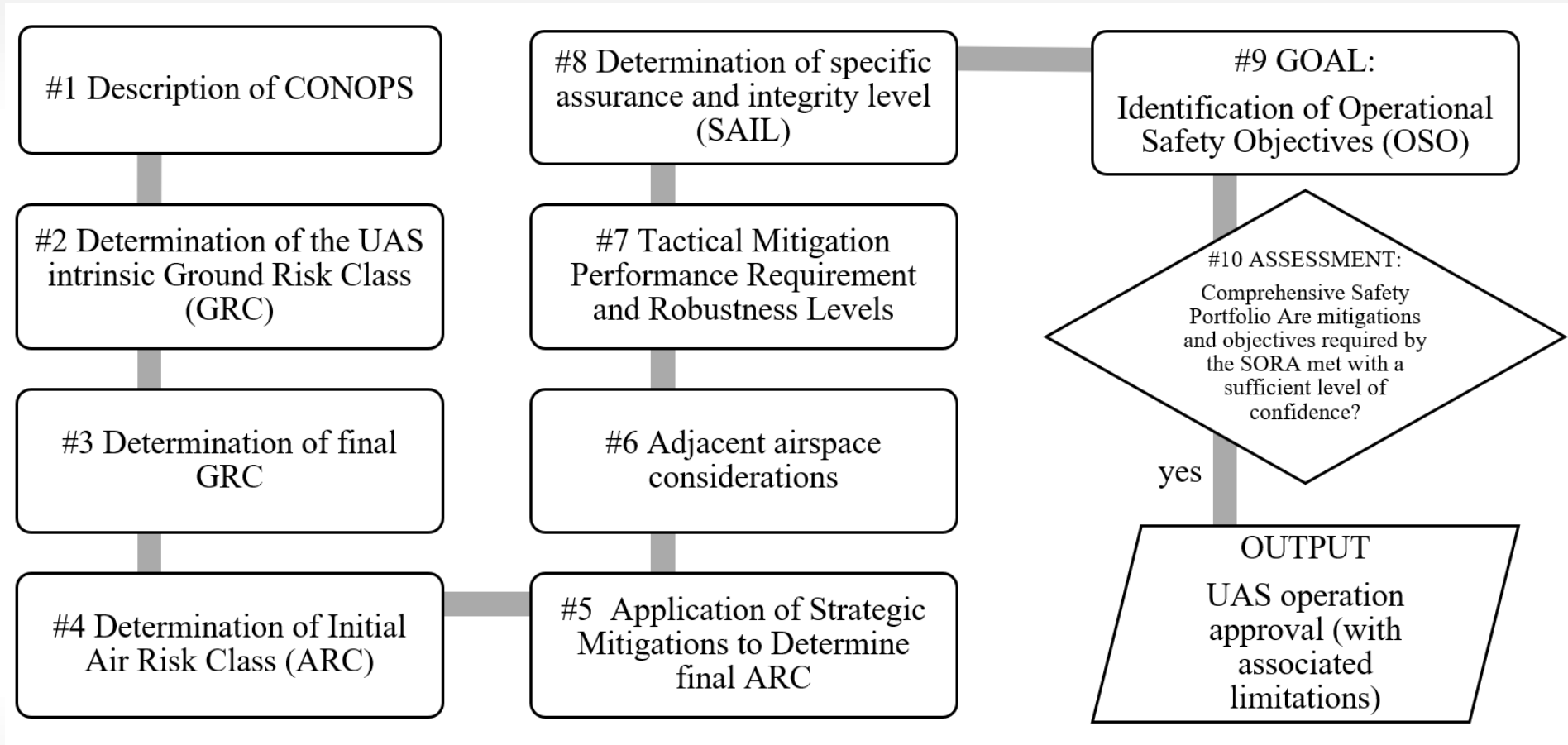
Lower complexity  
Lower Investment in tests  
Lower approval times

1. *Specific Operations Risk Assessment (SORA)*
2. *FAA ORDER 8130.34D*
3. *Risk Assessment Tool (RAT)*
4. *New/Proposed RAT*



01

# SORA



*Holistic approach: Ground and air risk classes;*

*Probability of catastrophic failure not calculated*

*No consideration with the population density*





02

## FAA Order 8130.34D

# 2. FAA ORDER 8130.34D

## Airworthiness Certification of Unmanned Aircraft Systems

Risk Category	Incremental Element	Value
<b>MTOW</b>	Up to 4.5 lbs	0
	4.5 up to 55 lbs	5
	55 lbs up to 300 lbs	10
	300 lbs up to 1,000 lbs	15
	Greater than 1,000 lbs	25
<b>Maximum Speed</b>	Less than 87 kts	0
	87 kts to 250 kts	10
	Greater than 250 kts	20
<b>Maximum Operating Altitude</b>	Less than 200 ft AGL	0
	200 ft AGL up to 500 ft AGL	5
	500 ft AGL up to 5,000 ft AGL	10
	5,000 ft AGL up to 17,999 MSL	15
	Class A and above	25
<b>Flight History</b>	previous flight time $\geq$ 50 hrs	0
	previous flight time < 50 hrs	2
	Unknown – first flight	6

Night Operations
IMC
Beyond or Extended Visual Line of Sight (BVLOS/EVLOS)
Chase Aircraft
Operations Closer Than 2 Miles From Towered Airport



Group Category	Total Score
Group I	0 to 16
Group II	17 to 39
Group III	40 and above

Applicant Task	Group I	Group II	Group III
Chartered Flight Area	Should be completed by applicant	Should be completed by applicant	Should be completed by applicant
Safety Checklist	N/A	Should be completed by applicant	Should be completed by applicant
Safety Evaluation	FAA only reviews program letter; questions resolved via email or phone	FAA determines if safety evaluation is necessary and the appropriate format	Should be completed
Initial Flight Test Plan	N/A*	Should be completed by applicant; Comprehensive review by FAA not required*	Should be completed by applicant*



Operational Limitations



03

## RAT: Risk Assessment Tool

## RAT General Description

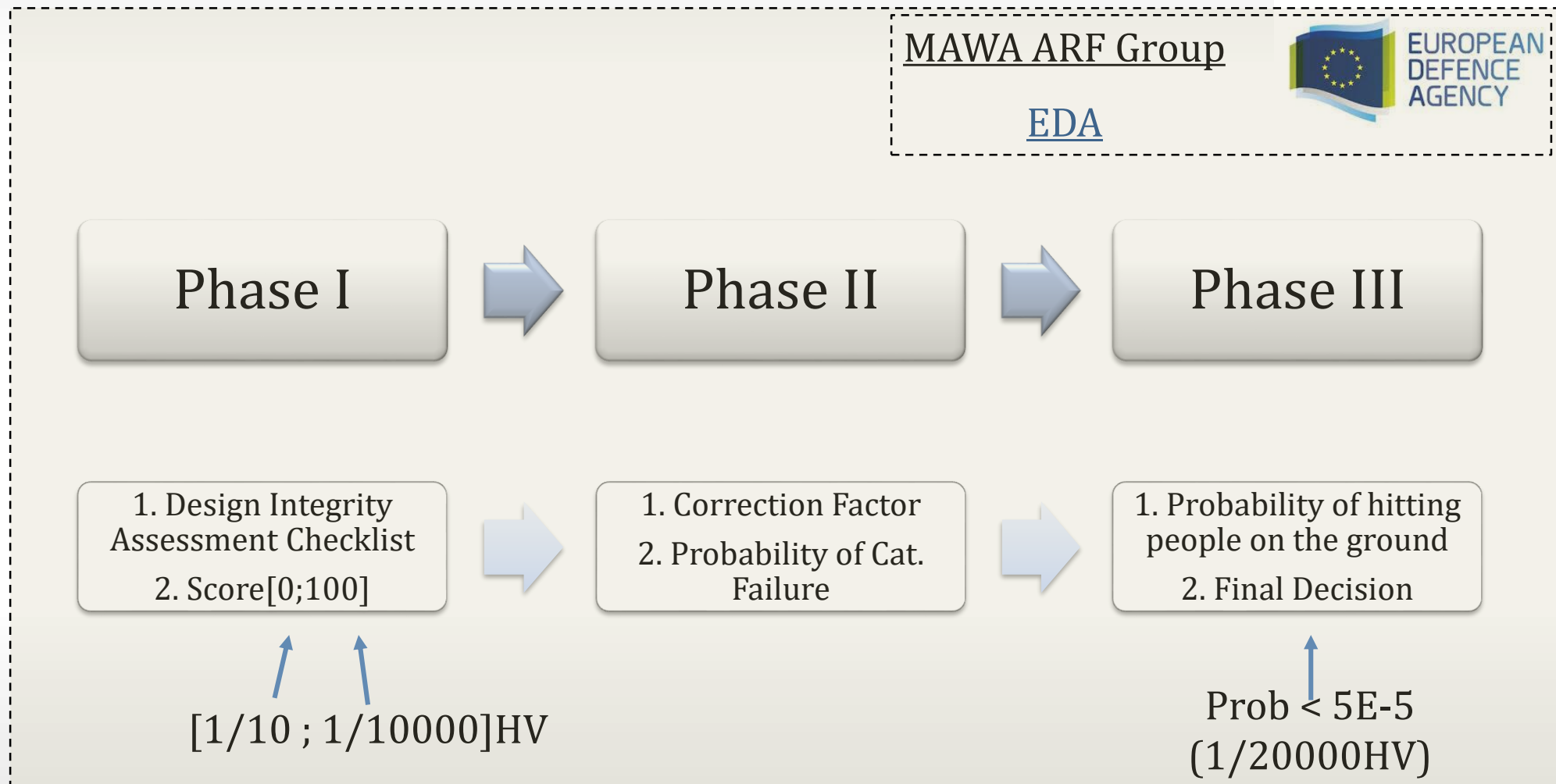
The RAT combines the probability of the loss of the UAV versus the probability of hitting people on the ground.

The calculation of the probability of the loss of the UAS is calculated as a function of a UAS Design Integrity Score which derives from the assessment of the Design Integrity over 11 safety relevant domains.

This score is then correlated with the probability loss of the UAS, allowing for the calculus of the probability of hitting people on the ground in accordance with the population density.

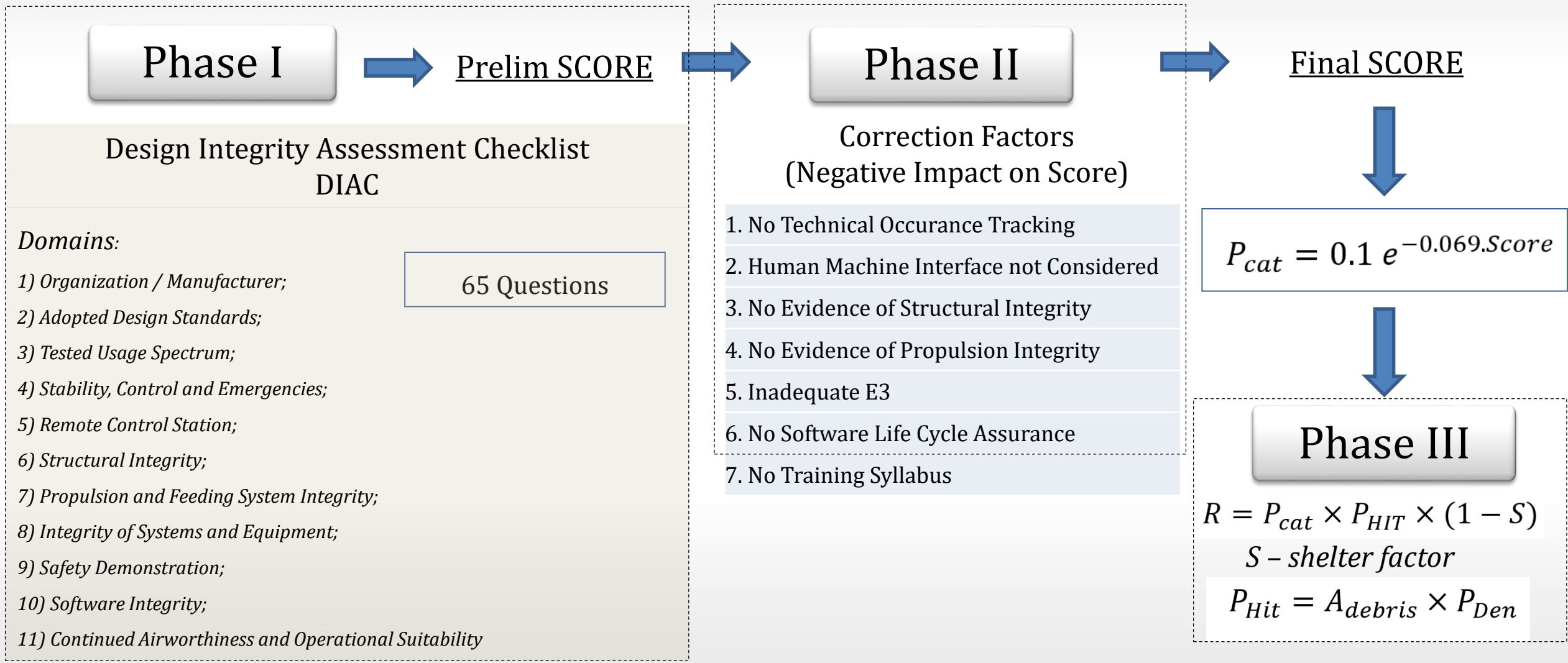


## RAT General Description



# 3. RAT

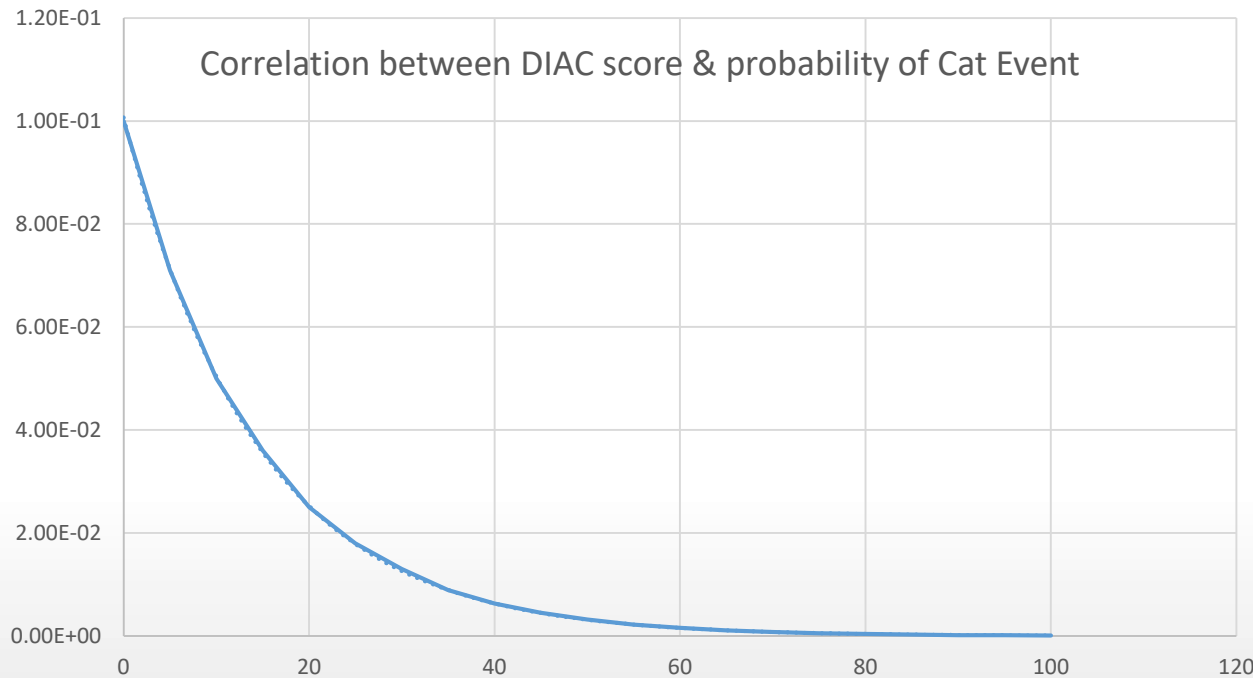
## RAT General Description



# 3. RAT

## RAT: Concepts & Terms

The correlation between the UAS design integrity score and the probability of a catastrophic event was derived by the UK NMAA and by the Italian NMAA and resulted in the following correlation:



$$f_{(\text{score})} = 0.1e^{(-0.069 \cdot \text{Score})}$$

## RAT: Concepts & Terms

The basic equation of the RAT is :

$$CE = PF \times (PD \times AL) \times PK \times S \quad (1)$$

where each variable is defined as:

CE = Casualty Expectation

PF = Probably of Failure or Mishap per flight hour

PD = Population Density per square mile.

AL = Lethal Area

PK = Probability of a Fatality given a hit (usually assumed to be 1)

S = Shelter factor (if applicable)

<sup>(1)</sup>Note: The equation is published in "Range Safety Criteria for Unmanned Air Vehicles , Rationale and Methodology Supplement, April 2001" issued by the Range Commanders Council/range Safety Group.



## RAT: Concepts & Terms

The probability of hitting people on ground is function of the wingspan, speed, maximum take-off weight of the platform and population density. The probability of hitting people on the ground is calculated as:

$$P_{Hit} = A_{debris} \times P_{Den}$$

$P_{HIT}$  – Probability of hitting people on the ground;

$A_{debris}$  – Crash/Impact area [m<sup>2</sup>];

$P_{Den}$  – Population density [people/m<sup>2</sup>].

$$A_{debris} = K \times b^2$$

$b$  - Wingspan [m];

$K$  – Dimensionless coefficient.

$$K = \min[50; E \times 17,5 + 3,2858] \quad (2)$$

<sup>(2)</sup>Note: This correlation was derived from experimental work conducted by the UK NMAA and the Italian NMAA.

# 3. RAT

## RAT: Concepts & Terms

The RAT tool is based on the risk matrix which combines the probability of the loss of the UAS versus the probability of hitting people on the ground. The risk equation is calculated as:

$$R = P_{cat} \times P_{HIT} \times (1 - S)$$

Where  
 R- Risk equation;  
 P<sub>HIT</sub> – Probability of hitting people on the ground;  
 P<sub>Cat</sub> – Probability of UAS catastrophic event;  
 S - Shelter factor.

This probability is then correlated with the kinetic impact energy of the UAS, allowing each NMAA to define different ranges of risk, that may be used as ranges of the risk matrix.

Risk criticality	Example of Risk criticality ranges
Unacceptable	>1E-3
Very High	>1E-4
High	1E-5 to 1E-4
Medium	1E-6 to 1E-5
Low	1E-7 to 1E-6
Very Low	<1E-7

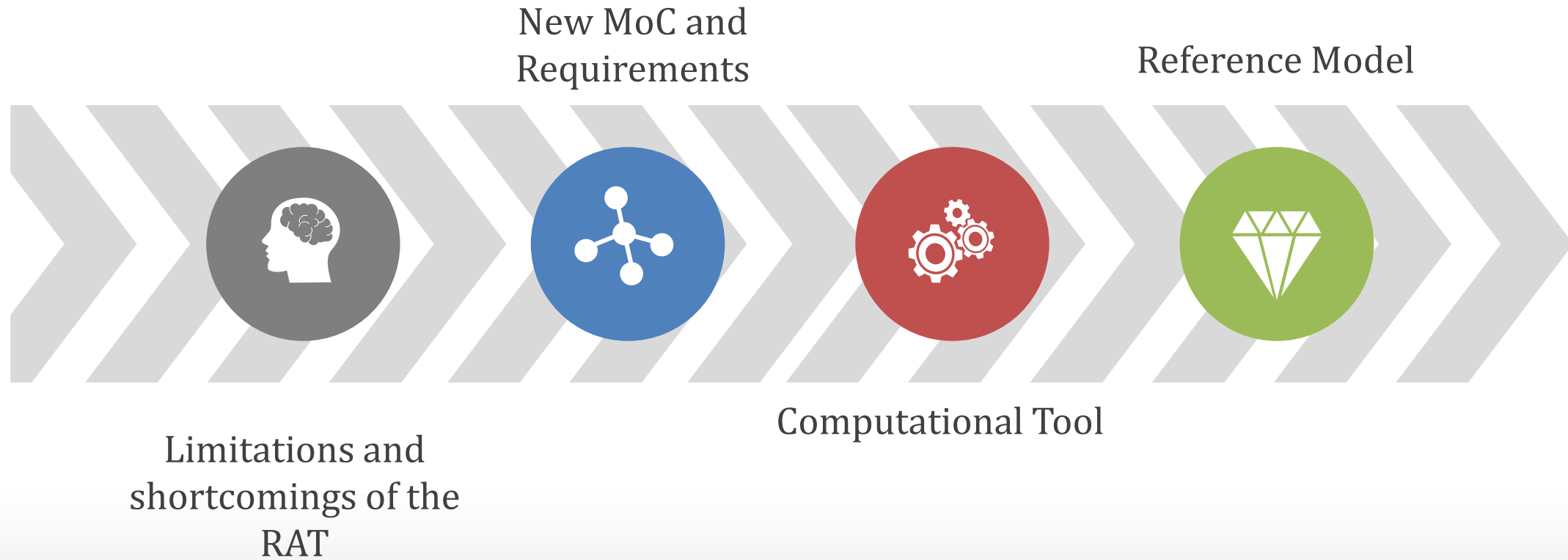


04

## PRAT: Proposal for new RAT

# 4. New/Proposed RAT

## Development










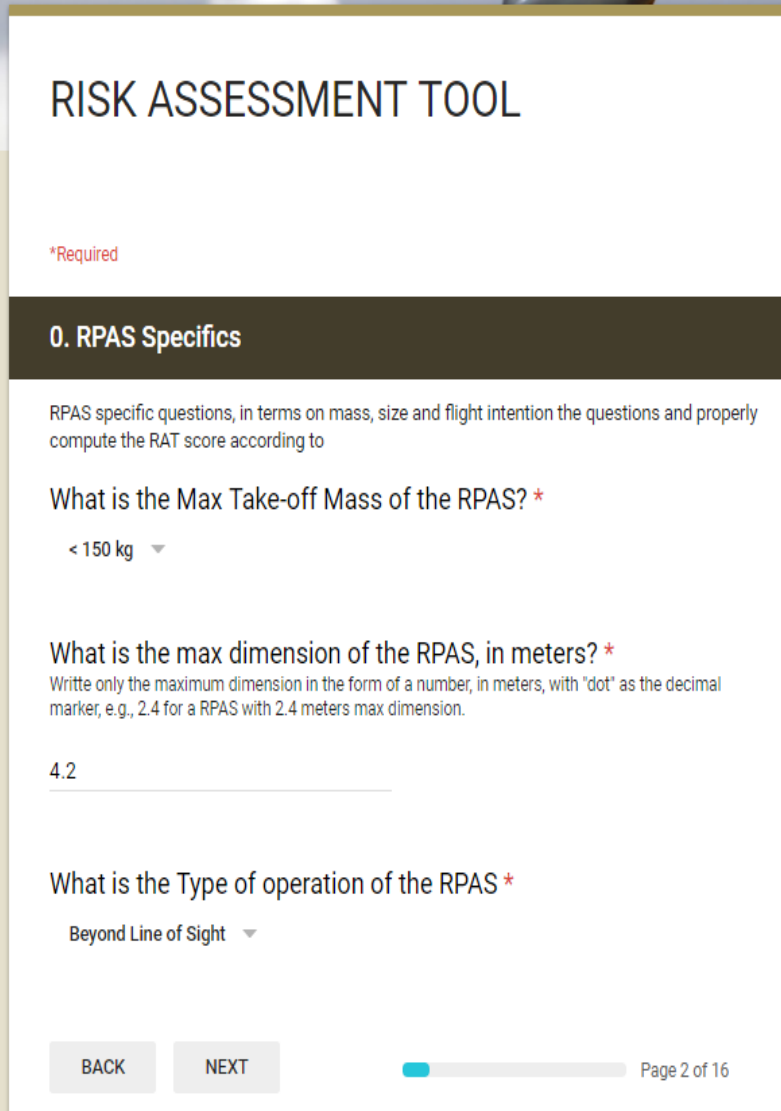
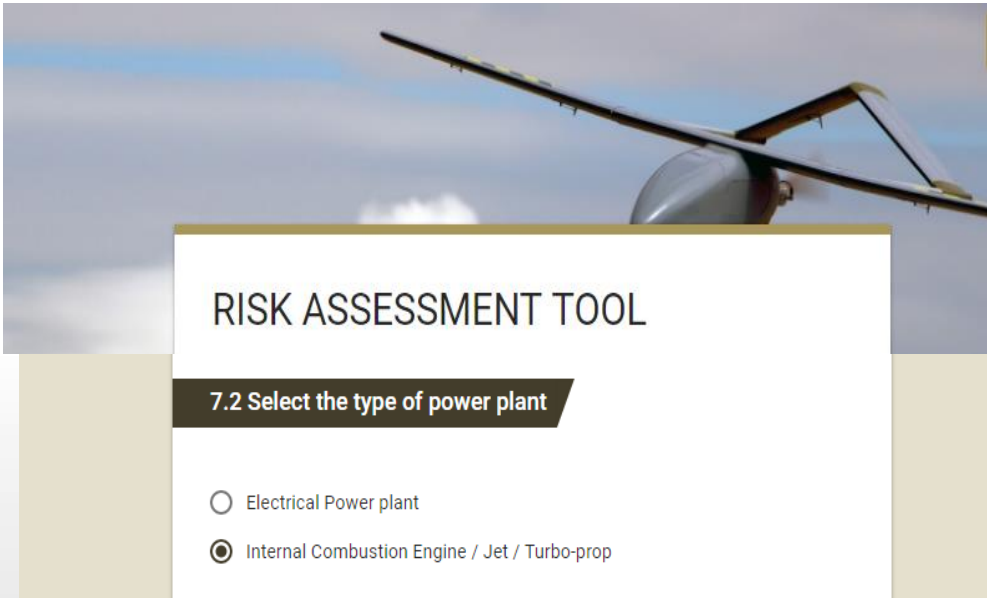
OBJECTIVE: Change the *Risk Assessment Tool* in order to allow the **standardization** of the airworthiness evaluations of these systems in the European Space.

- 1 – Identify the limitations of the RAT that have led the Nations not to invest in trying to use the RAT in a consensual manner.
- 2 – Define requirements and respective MoCs in a clear and unambiguous way so that the evaluators could achieve consensual answers.
- 3 – Transform the tool in a way that it could be used by different specialists, stationed in different locations, and share in a common platform their results.
- 4 – Define a reference scenario that can be used to answer in an immediate way the allowable operation areas (in the National Territory) for a given UAS (with a specific design integrity score).

# 4. New/Proposed RAT

## The Tool

-  Open Source
-  Multi-platform
-  Automatic Saving
-  Document Upload
-  Remote access



# 4. New/Proposed RAT

## PRAT: Validation

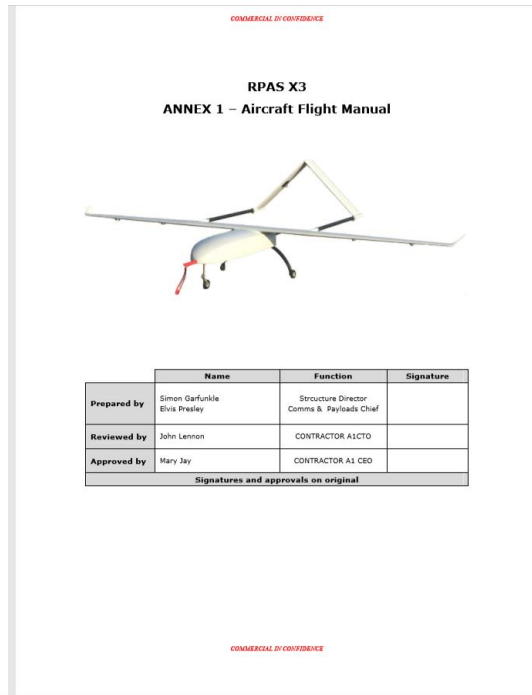
### Case Study

UAS

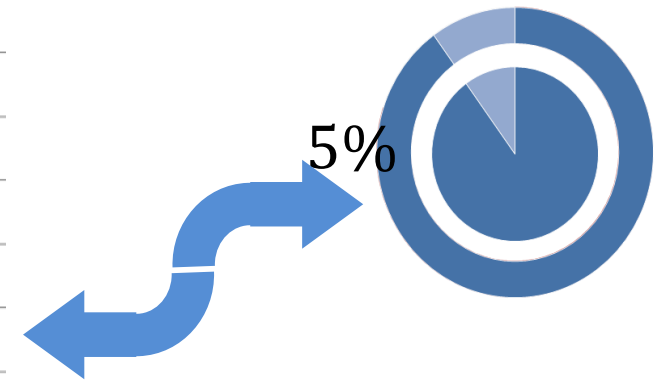
SPAN of 4.2 m

MTOW 35 kg

Answers by:  
MAWA ARF Group **EDA**

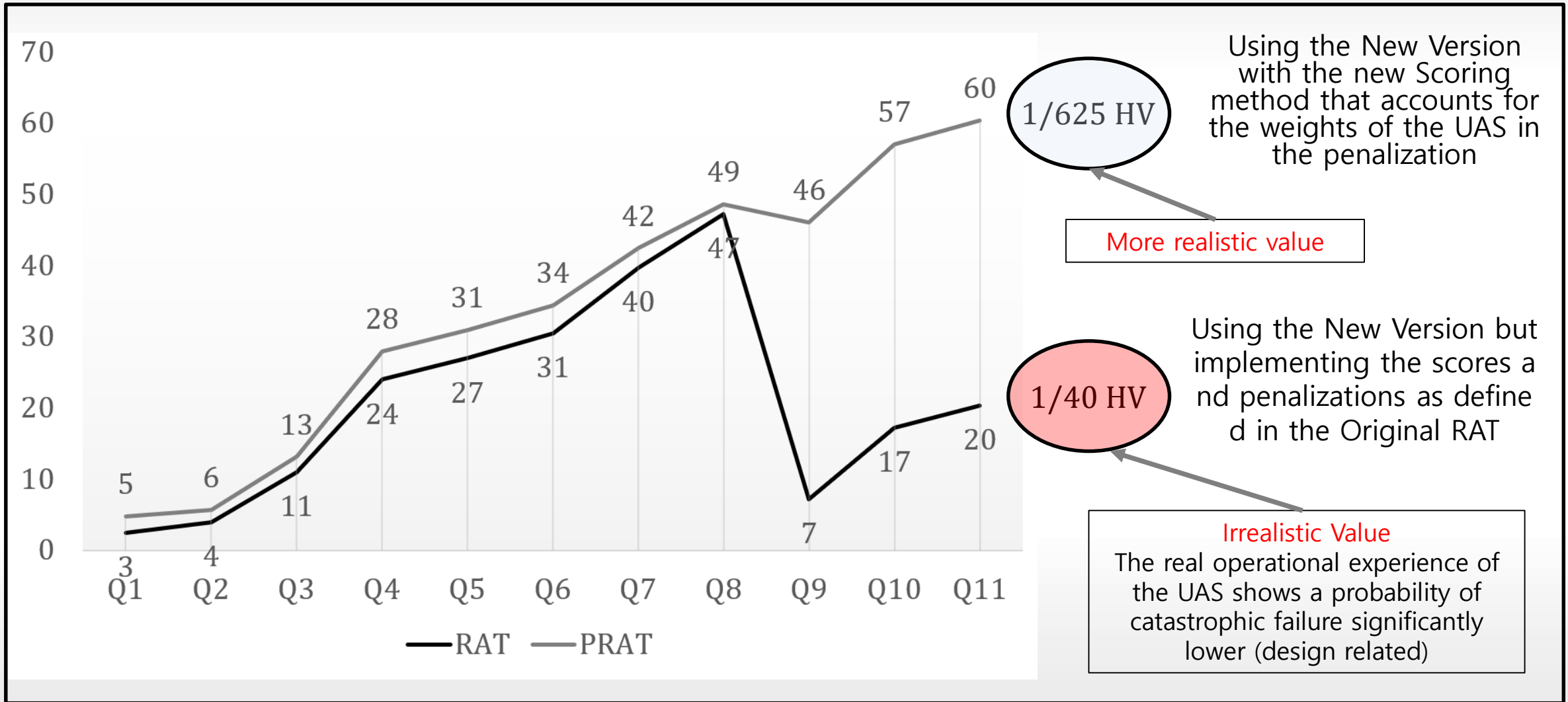


Specialist	Score
E1	65
E2	39
E3	56
E4	52
E5	73
E6	44
<b>Average</b>	<b>55</b>
<b>Baseline</b>	<b>60</b>



# 4. New/Proposed RAT

## PRAT: Validation



# 4. New/Proposed RAT

## PRAT: Comparison to the RAT for different weights

Study of the applicability of the RAT to different types of UAS.

This study considered that the scenario evaluated by the NMAAs in the field exercise was the same for the different types of systems. Specifically, the same conditions and experience of the manufacturer, the same systems and same documentation was assumed to have been delivered for evaluation.

Model	UAV ref	m [kg]	$V_{\text{impact}}$ [m/s]	b[m]	Score	Probability of Catastrophic failure	Pop. density people/Km <sup>2</sup>
RAT	Raven	2	23	1.5	10	4.9E-02	13
PRAT					57	2.0E-03	330
RAT	ANTEX X02 Alfa	13	30	2.4	10	4.9E-3	5
PRAT					64	1.2E-3	200
RAT	Scan Eagle	20	35	3	10	4.9E-02	3
PRAT					52	2.7E-03	50
RAT	Wingo	35	35	4.2	10	5.0E-02	1.5
PRAT					50	3.0E-03	25
RAT	Shadow	200	75	6	10	4.9E-02	0.21
PRAT					32	1.1E-02	0.9
RAT	Hermes 900	1000	200	20	10	4.9E-02	0.005
PRAT					5	7.1E-02	0.0035



SMALL UAS:

The new version of the RAT seems to produce scoring results that when transformed into values of probability of catastrophic failure make more sense than the ones obtained with the application of the scoring based on the initial version.

LARGER UAS:

The differences obtained using both methods are insignificant.

## 4. New/Proposed RAT

# PRAT: Building The Reference Model

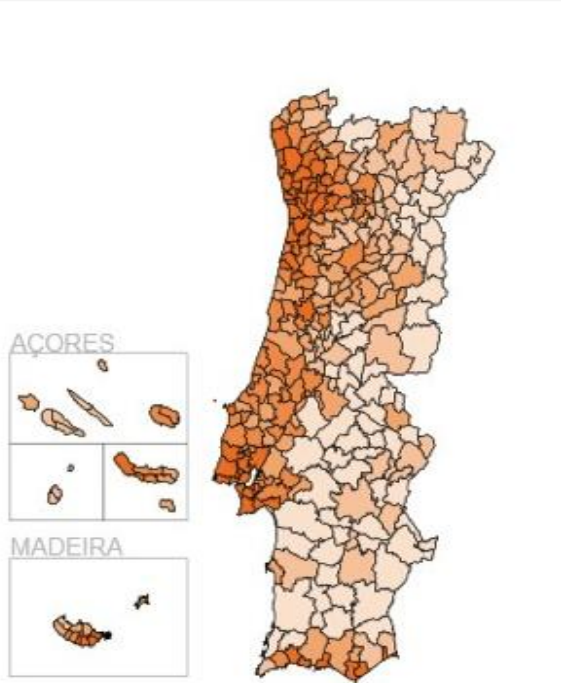
The definition of the usage spectrum was made with the simulations provided by the new version of the RAT, which were complemented with engineering judgements that derived from the development of this work:

- Harmless UAS (as defined in SLAT) they could fly without restrictions;
- The study showed that a 10 % of variation between results of evaluators must be “absorbed” by the methodology;
- For the case of evaluations of medium/large UAS, scores that result superior to 90%, require that the safety assurance level that must be demonstrated to comply with this tool is so high, that probably the certification of those platforms in the light of STANAG 4703 would be possible, if such a process was endorsed.

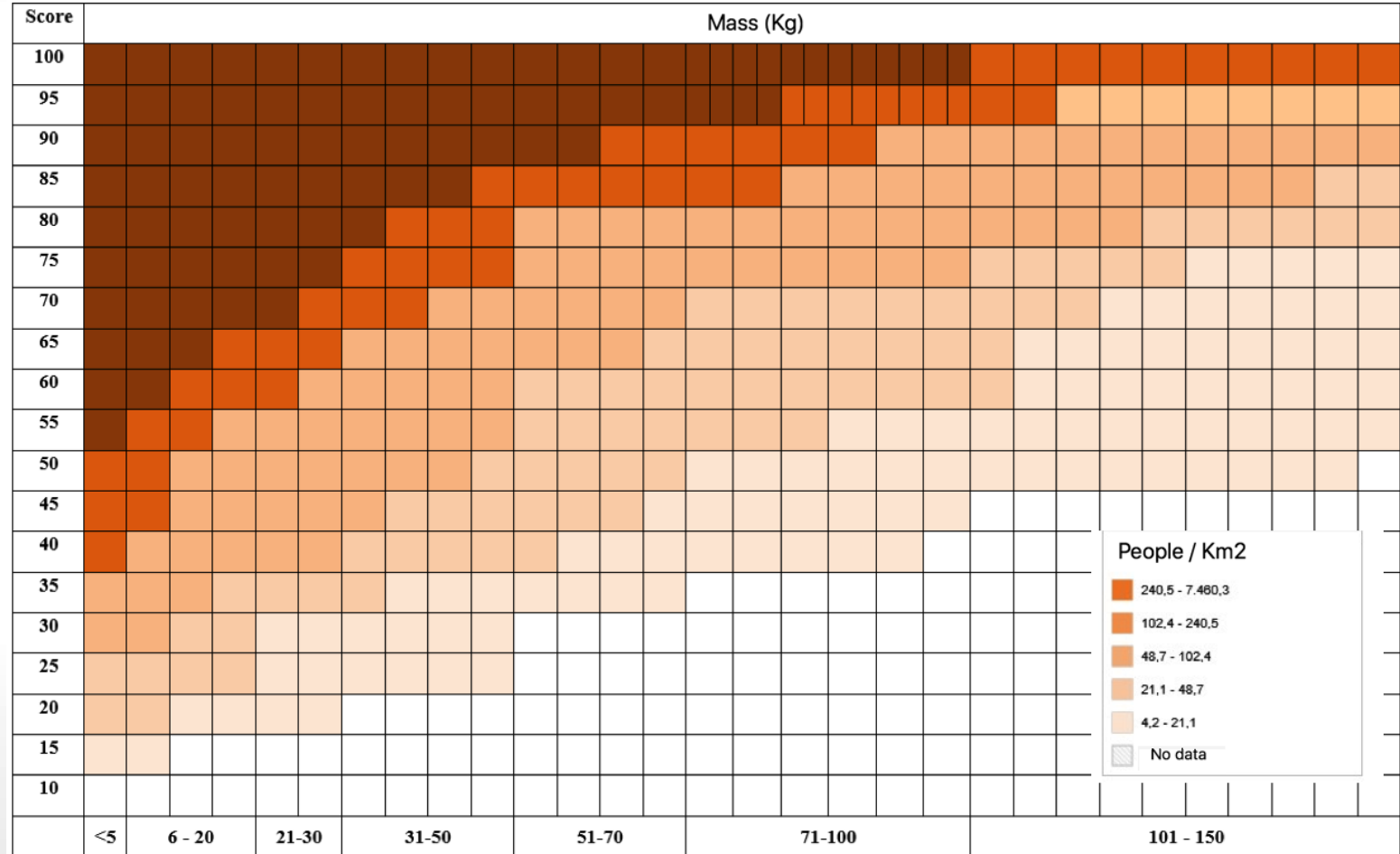


# 4. New/Proposed RAT

## PRAT: Building the Reference Model

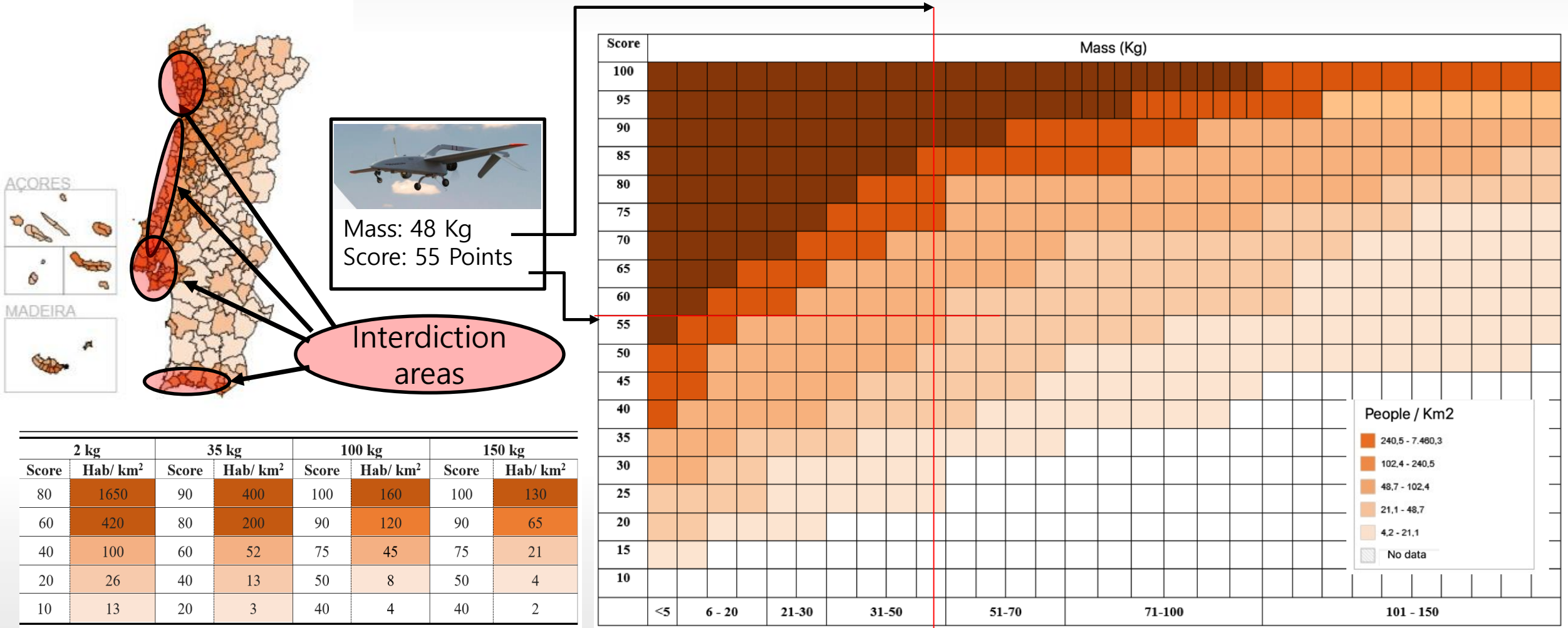


2 kg		35 kg		100 kg		150 kg	
Score	Hab/ km <sup>2</sup>	Score	Hab/ km <sup>2</sup>	Score	Hab/ km <sup>2</sup>	Score	Hab/ km <sup>2</sup>
80	1650	90	400	100	160	100	130
60	420	80	200	90	120	90	65
40	100	60	52	75	45	75	21
20	26	40	13	50	8	50	4
10	13	20	3	40	4	40	2



# 4. New/Proposed RAT

## PRAT: Building the Reference Model





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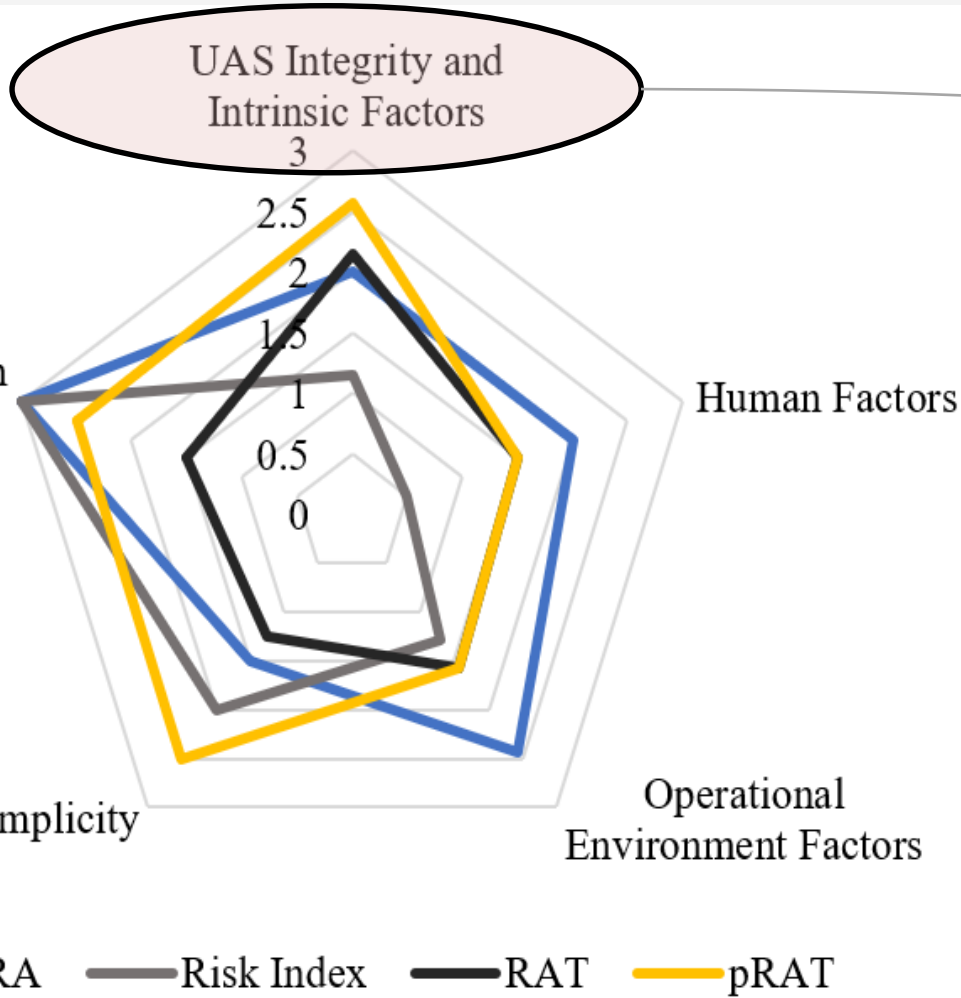
## Comparison

# 5. Discussion

Factor Group	Description	Framework			
		SORA	Risk Index	RAT	pRAT
	Applicability (class or category)	Specific	R&D crew training, market survey, production flight testing	<i>Open and Specific</i>	<i>Open and Specific</i>
<b>Intrinsic Factors (quality, safety)</b>	UAS characteristics	+++	++	+	+++
	Structural Integrity and Safety	++	+	+++	+++
	Software and System's Integrity	+	+	+++	+++
	Operational/testing flight time	+	-	+++	+++
	Life cycle estimation and support	++	++	+++	+++
	Probability of Catastrophic failure	++	++	++	+++
	Collision avoidance	+++	-	-	-
<b>Human Factors</b>	Operator Training and Qualifications	++	+	++	++
	Human Error	++	-	+	+
<b>Operational Environment</b>	Operations outside design standards	+++	+	++	++
	Probability of failure to operational reasons (weather, environment)	+++	+	+	++
	Infrastructure Damage estimation	++	+	-	-
	Populational density	++	+++	+++	+++
	Probability of causing death of people on the ground	+	+	+++	+++
	Probability of collision in flight	+++	++	-	-
	Geofencing	+++	-	-	-
	<b>Complexity<sup>1</sup></b>	+++	++	+++	++
	<b>Standardization Potential</b>	+++	+++	+	++

<sup>1</sup> + low complexity; ++ medium complexity; +++ high complexity;

□

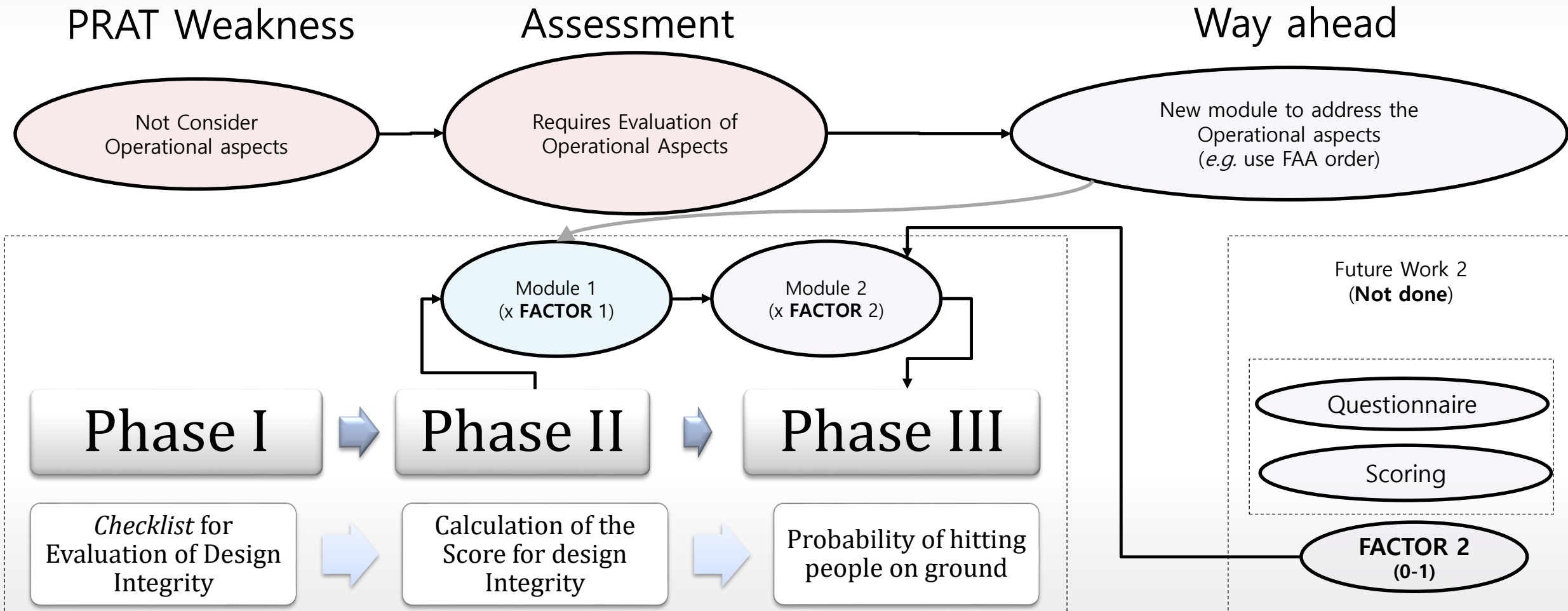


Main strength

The RAT (when compared with other risk assessment tools) covers in a very objective and thorough way the most important aspects addressed in the STANAG 4703.

# 5. Discussion

## PRAT: Improving the Tool







06

## Conclusions

- The Proposed tool, without further developments:
  - Is considered to be amongst the best tool available to compare different UAS, as it provides a very thorough evaluation of the UAS;
  - Is considered to be in conditions of being incorporated in the UAS documentations as one of the reference Risk based methodologies to be used as an adequate Means of Compliance for the UAS-MIL Specific category.
- The new Version of the RAT is a very good Tool for the assessment of the design integrity;
- The new version is more user friendly;
- The results obtained in the validation exercise show that the tool allows for the scoring of system with reduced variability;
- The RAT was developed only for the assessment of the design integrity, which is a weak point when compared to other methodologies, which are more inclusive;
- This tool can be easily upgraded in order to respond to aspects as human factors and operational consideration( in the same manner as the design assurance was accounted for);
- The consideration of these factors through a typified analysis could make the RAT possible to be used in a broader scope;

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NATO, "STANAG 4703 Light Unmanned Aircraft Systems Airworthiness Requirements," NSO, 2 ed., 2016.

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PorData, "Population Density of Portugal," 2018. [Online]. Available: <https://www.pordata.pt/Municipios/Densidade+populacional-452>. [Accessed on 02 05 2018].



## IMAGES:

[1] <https://i.ytimg.com/vi/JAGzRR-UufE/maxresdefault.jpg>

[2] <http://www.thehindu.com/news/national/tamil-nadu/uav-crashes-into-coconut-grove/article5457371.ece>

[3] <https://www.mirror.co.uk/news/weird-news/drones-smashes-planes-wing-terrifying-5939459>

[4] <https://theaviationist.com/2013/12/19/drone-survival-guide/>

[5] <https://www.pordata.pt/Municipios/Densidade+populacional-452>

[6] [https://www.researchgate.net/publication/232271708\\_Reconfigurable\\_unmanned\\_aerial\\_vehicles/figures?lo=1](https://www.researchgate.net/publication/232271708_Reconfigurable_unmanned_aerial_vehicles/figures?lo=1)

[7] <https://www.boeing.com/defense/autonomous-systems/scaneagle/index.page>

[8] <https://www.upi.com/Defense-News/2017/01/09/US-Army-selects-Textron-for-Shadow-UAV-sustainment/7311483978900/>

[9] <http://elbitsystems.com/product/hermes-900-5/>

THANK YOU



*“Now this is not the end.  
It is not even the beginning of the end. But it is, perhaps, the end of the beginning.”*

Winston Churchill